

# MCP1.1 Biotic interactions

**13 avril 2023**

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ImHorPhen Bioimaging Research Group



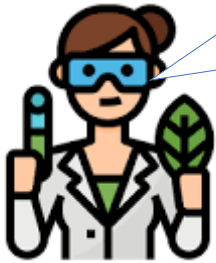
**anr**<sup>®</sup>  
agence nationale  
de la recherche  
AU SERVICE DE LA SCIENCE  
ANR11-INBS-0012

**INRAE** **ARVALIS**

**Terres  
Inovia**  
l'agronomie en mouvement

- The quest of genericity

Identify phenological stages, measure of size of symptoms, detect change of color, characterize change turgescence, monitor germination, determine shape of a leaf,, extract roots out of soil, count nodules on roots, quantifying amount of inoculum,, detect emergence, monitor kinetic of symptoms, ...SO MANY DIFFERENT BIOLOGICAL QUESTIONS !!!



Biologist

I don't have time to do it all since I am the only one on the platform please have look at the jungle of image processing tools already available on <https://www.quantitative-plant.org/software>



Geek1.0

- Deep learning as a generic tool

Identify phenological stages, measure of size of symptoms, detect change of color, characterize change turgescence, monitor germination, determine shape of a leaf,, extract roots out of soil, count nodules on roots, quantifying amount of innoculum,, detect emergence, monitor kinetic of symptoms, ...



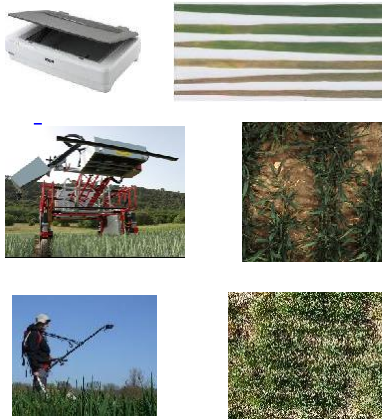
Biologist

From a computer perspective all of these can be sorted in classification, segmentation, tracking and addressed with a very limited number of available neural networks : ResNet, Unet, CNN-LSTM, with help of Phenome I propose make them available in a didactic way on 4P and train all geeks and tech minded biologist to use these tools



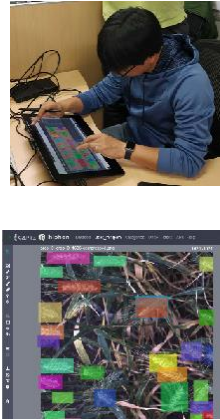
Computer scientist

## Step 1 image acquisition



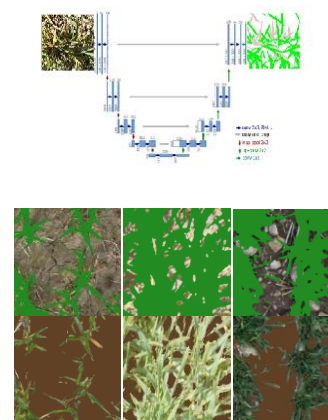
from past and future  
funded experiments

## Step 2 annotation



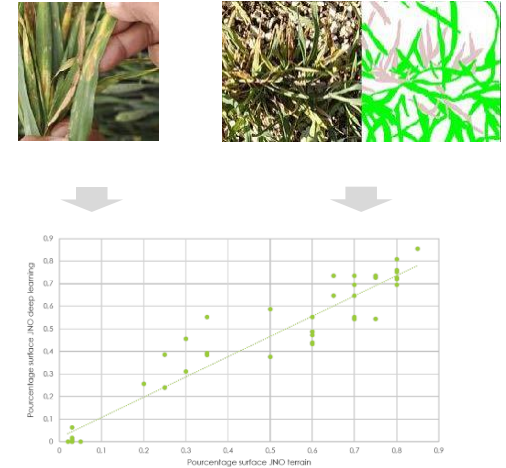
from collaborative  
platform

## Step 3 Deep learning



from didactic version of  
U-Net

## Step 4 Data analysis



Comparison with ground truth  
Automatic cluster of types of errors

## Step 1 image acquisition



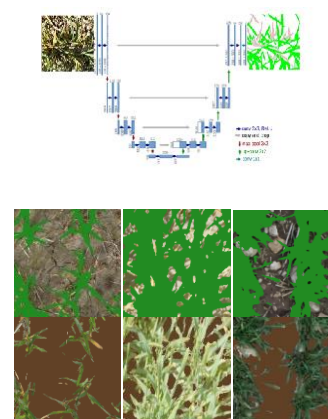
from past and future  
funded experiments

## Step 2 annotation



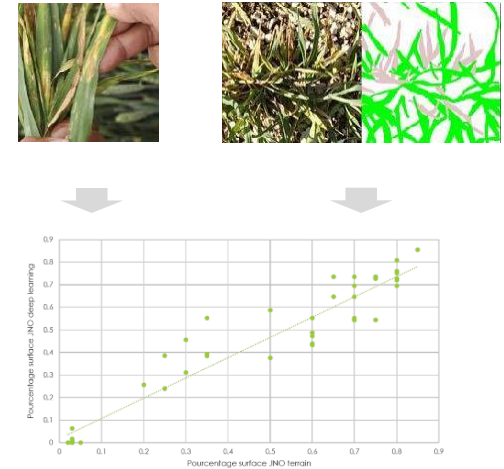
from collaborative  
platform

## Step 3 Deep learning

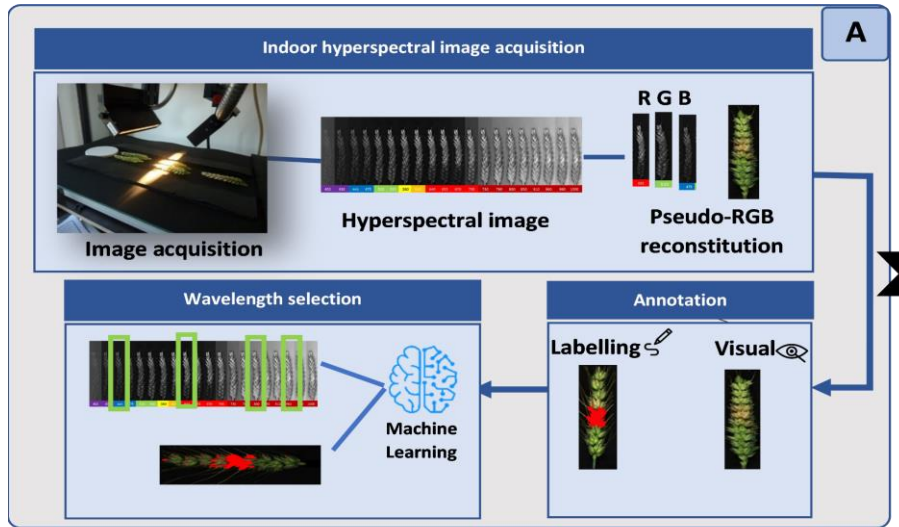


from didactic version of  
U-Net

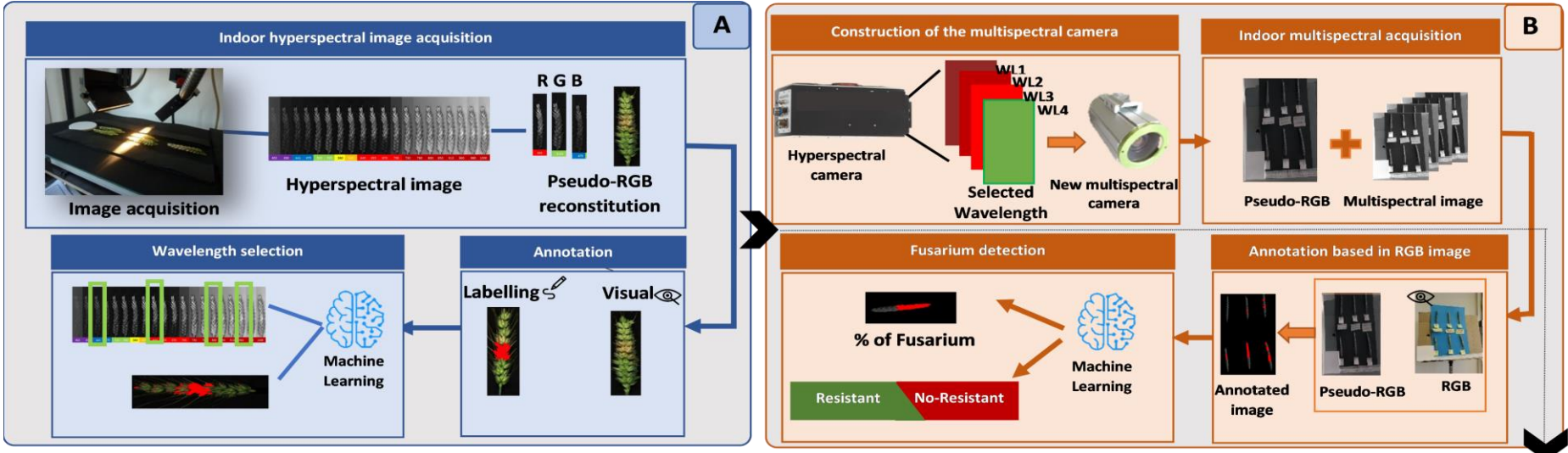
## Step 4 Data analysis



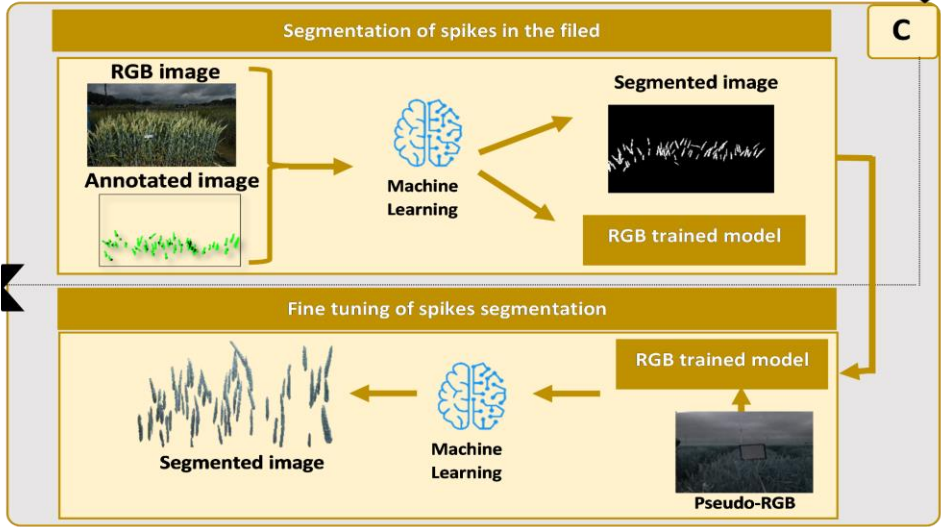
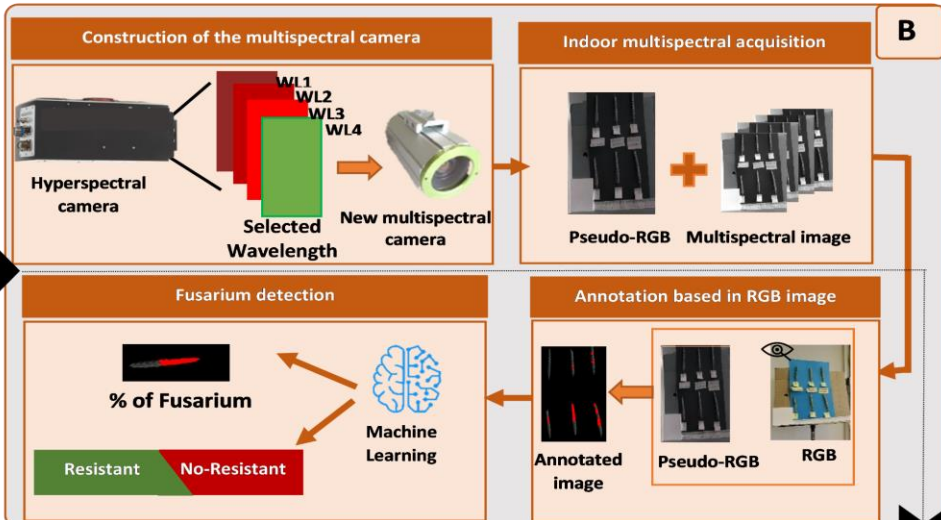
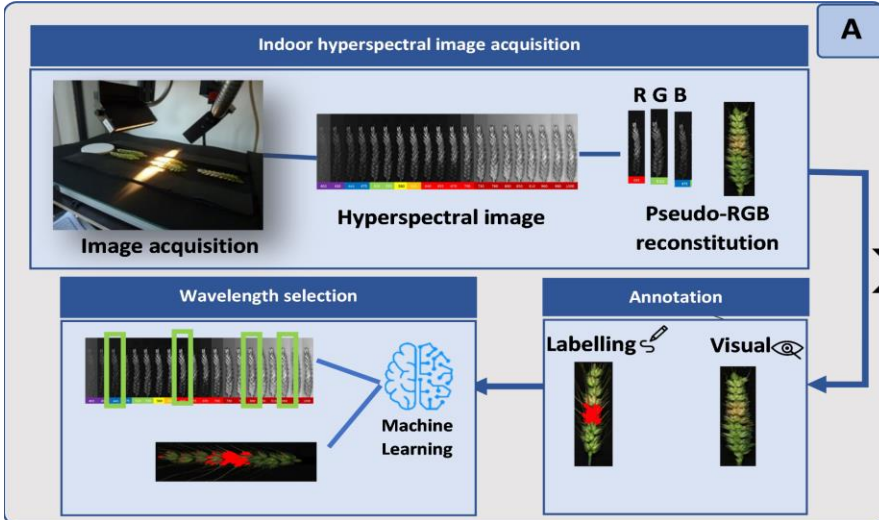
Comparison with ground truth  
Automatic cluster of types of errors



# New methodology on image acquisition

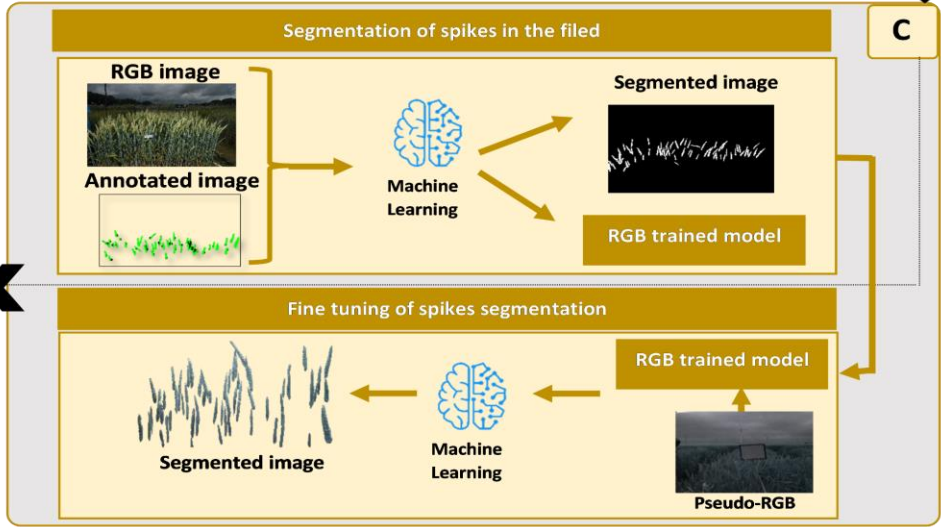
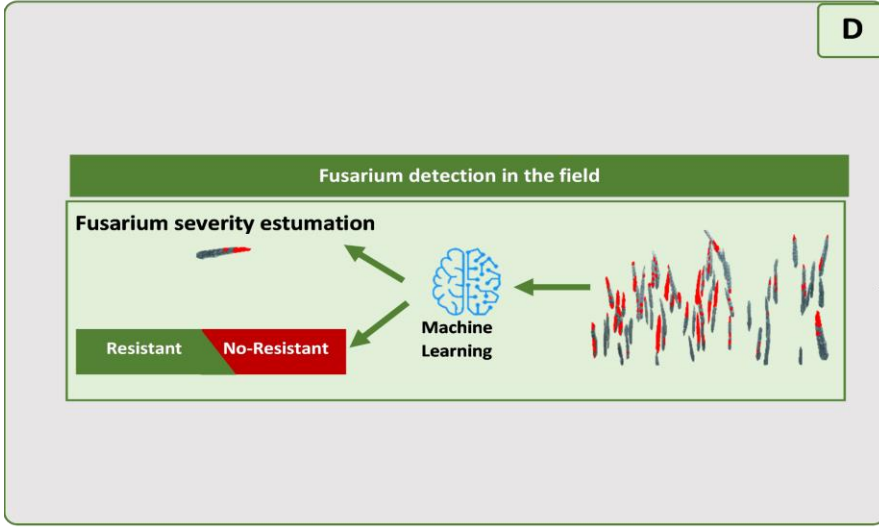
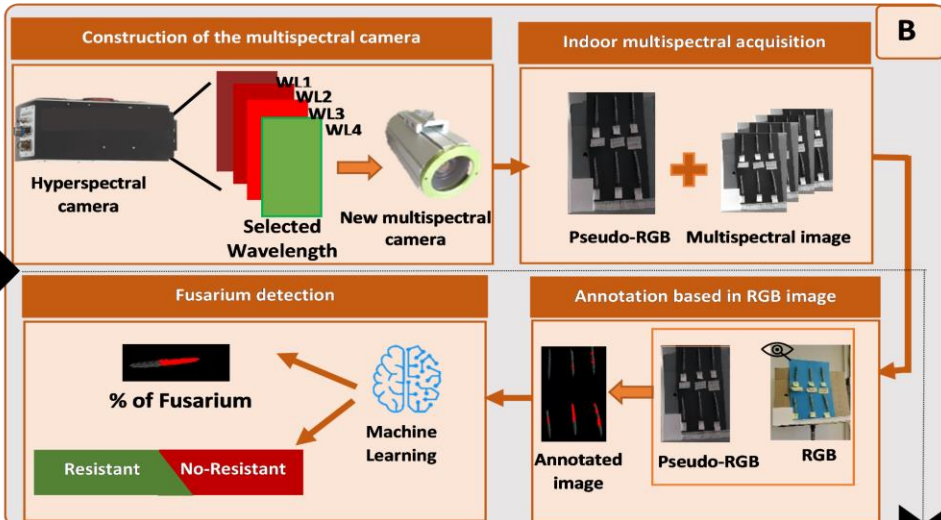
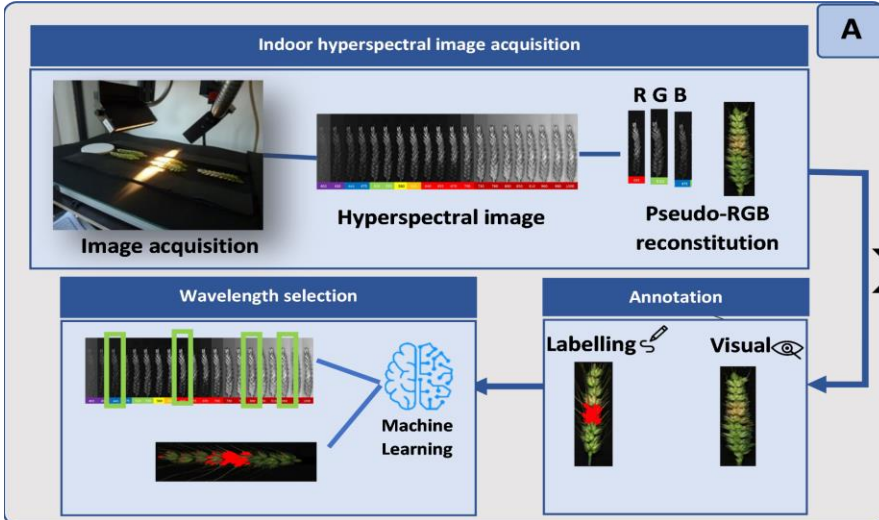


# New methodology on image acquisition





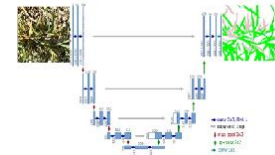
# New methodology on image acquisition



Réseau de neurone pour la segmentation

Présenté lors de formation PHENOME

Vidéo tutoriel le disponible sur chaîne youtube par Ali Ahmad



YouTube FR

Rechercher

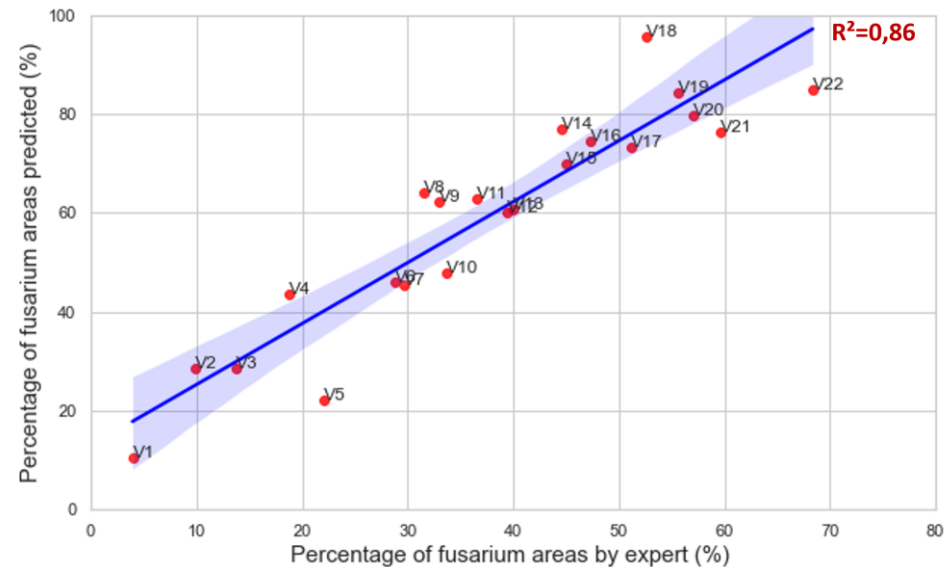
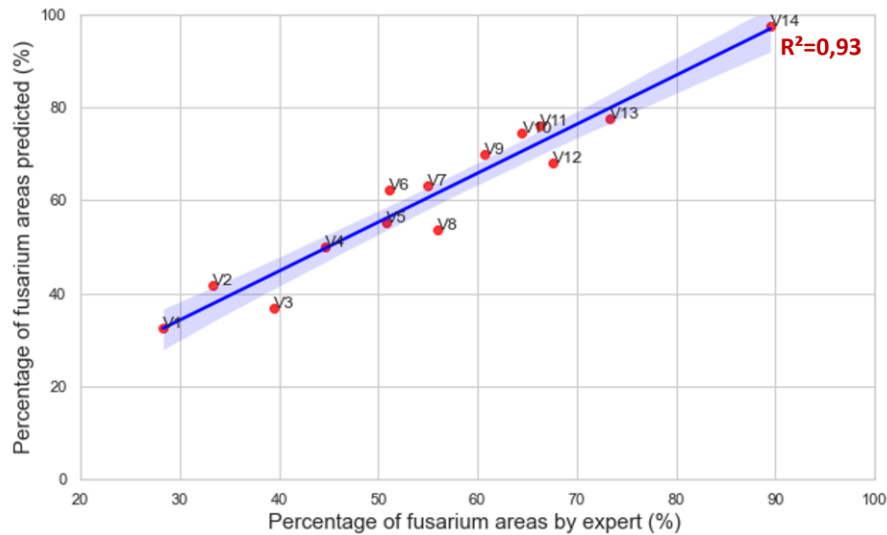
```
ESRF_Seg_Hands_on - Google D: x | U-Net Segmentation notebook: x | +
colab.research.google.com/drive/TK6vY9IMafco05pQz3E3Z75F7ES95Iaw#scrollTo=AE5CWvYnEZCQ
Unet Segmentation notebook.ipynb
Code | Tests
Epoch 1/20 [.....] - ERM: 0.7424 - dice_coefficient: 0.3387
Epoch 00001: saving model to /content/gdrive/Drive/ESRF_Seg_Hands_on/test_model_01
75/75 [.....] - 124 18064/step - loss: 0.7424 - dice_coefficient: 0.3387 - val_loss: 0.8908 - val_dice_coefficient: 0.3548
Epoch 2/20 [.....] - ERM: 0.5705 - dice_coefficient: 0.6515
Epoch 00002: saving model to /content/gdrive/Drive/ESRF_Seg_Hands_on/test_model_02
75/75 [.....] - 124 18064/step - loss: 0.5705 - dice_coefficient: 0.6515 - val_loss: 0.5822 - val_dice_coefficient: 0.6925
Epoch 3/20 [.....] - ERM: 0.4812 - dice_coefficient: 0.7958
Epoch 00003: saving model to /content/gdrive/Drive/ESRF_Seg_Hands_on/test_model_03
75/75 [.....] - 124 18064/step - loss: 0.4812 - dice_coefficient: 0.7958 - val_loss: 0.5094 - val_dice_coefficient: 0.8123
Epoch 4/20 [.....] - ERM: 0.4493 - dice_coefficient: 0.8249
Epoch 00004: saving model to /content/gdrive/Drive/ESRF_Seg_Hands_on/test_model_04
75/75 [.....] - 124 18064/step - loss: 0.4493 - dice_coefficient: 0.8249 - val_loss: 0.3874 - val_dice_coefficient: 0.8792
Epoch 5/20 [.....] - ERM: 0.4281 - dice_coefficient: 0.8782
Epoch 00005: saving model to /content/gdrive/Drive/ESRF_Seg_Hands_on/test_model_05
75/75 [.....] - 124 18064/step - loss: 0.4281 - dice_coefficient: 0.8782 - val_loss: 0.4856 - val_dice_coefficient: 0.8126
Epoch 6/20 [.....] - ERM: 0.4102 - dice_coefficient: 0.8992
!! # Plot training & validation curves
plt.figure(figsize=(10, 5))
```

23:23 / 31:33

UNET demo

<https://www.youtube.com/watch?v=wOmJnn3NrvE&t=1402s>

*Fusarium* detection by machine learning methods on segmented images acquired in the field environment using the CMS4 camera.



## Step 1 image acquisition



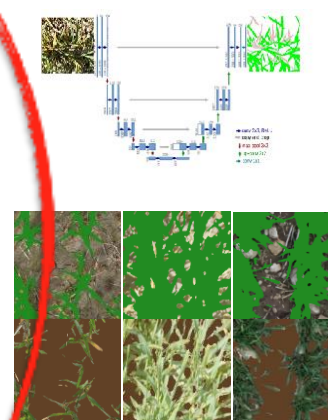
from past and future  
funded experiments

## Step 2 annotation



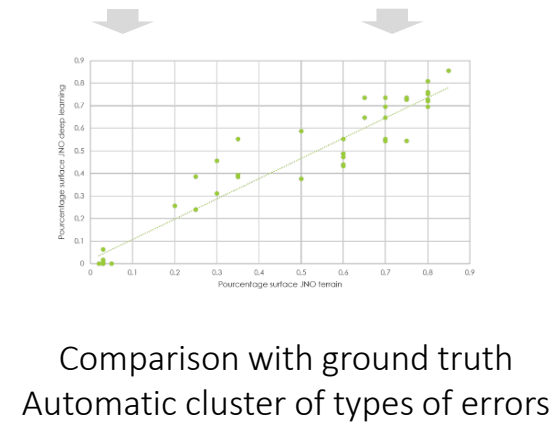
from collaborative  
platform

## Step 3 Deep learning



from didactic version of  
U-Net

## Step 4 Data analysis



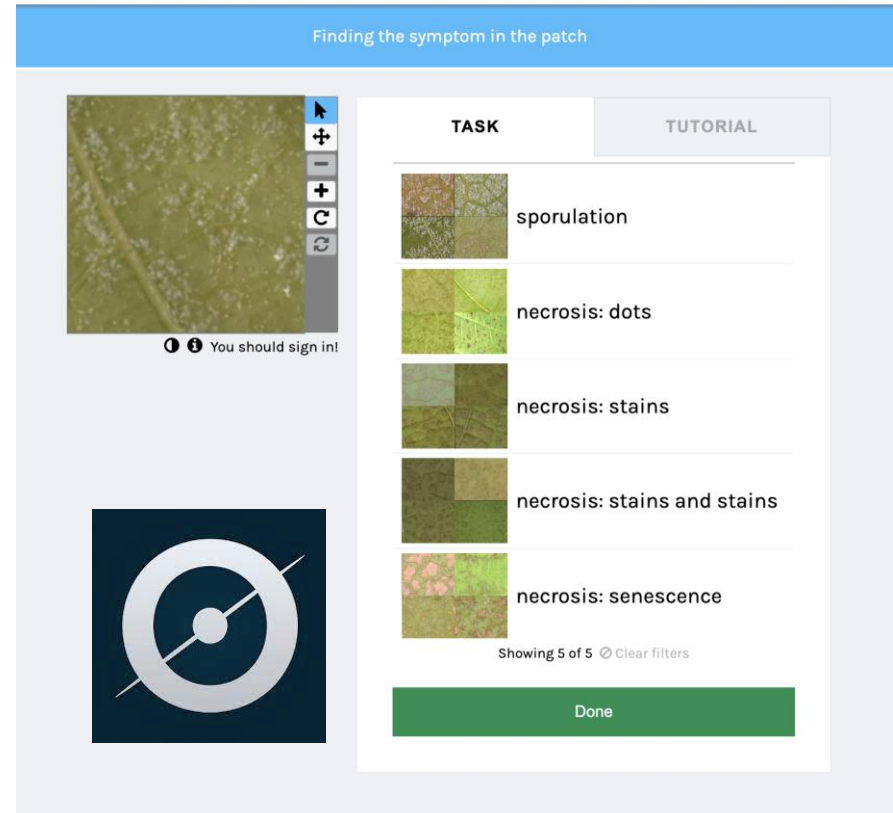
## Disques foliaires et mildiou

OIV 452-2

- Décrit interaction disque foliaire vigne et mildiou
- Aggrège sporulation et nécrose sur une échelle de résistance avec des valeurs impaires de 1 à 9
- Complexe ->
  - N'est pas toujours utilisé
  - Souvent seule la sporulation est prise en compte



Finding the symptom in the patch



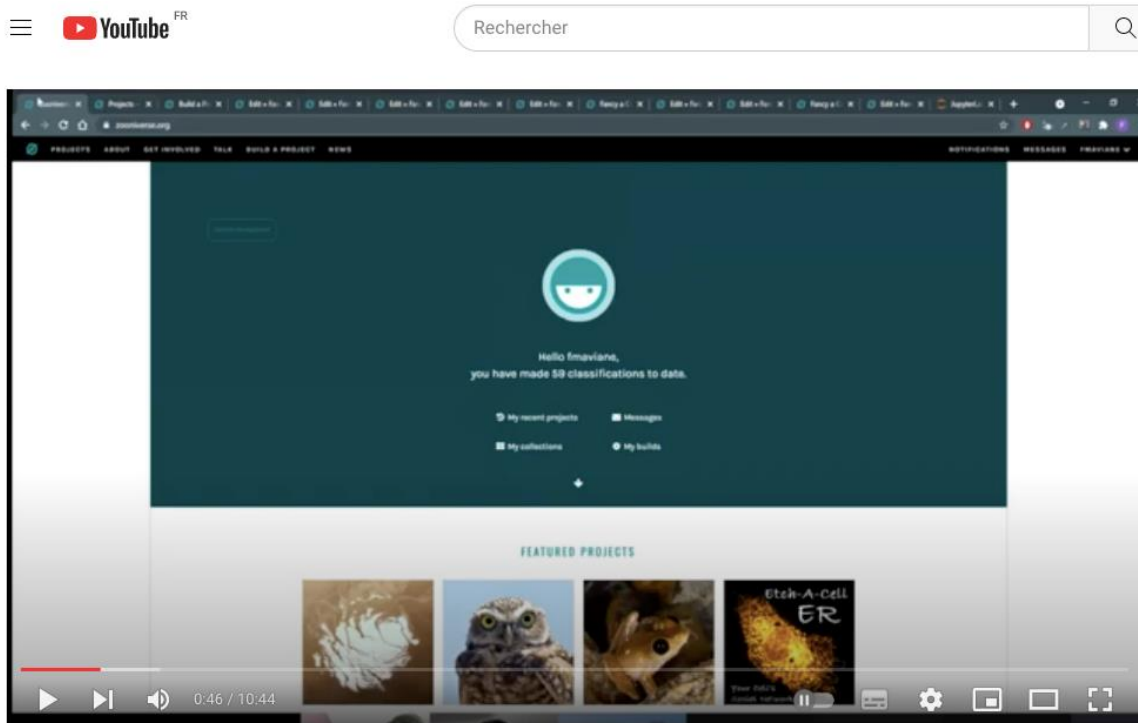
**TASK** **TUTORIAL**

- sporulation
- necrosis: dots
- necrosis: stains
- necrosis: stains and stains
- necrosis: senescence

Showing 5 of 5 [Clear filters](#)

Done

Outil collaboratif d'annotation en ligne DIY  
Présenté lors de formation PHENOME  
Vidéo tutoriel le disponible sur chaîne youtube par Felicia



Annotation with ZOONIVERSE

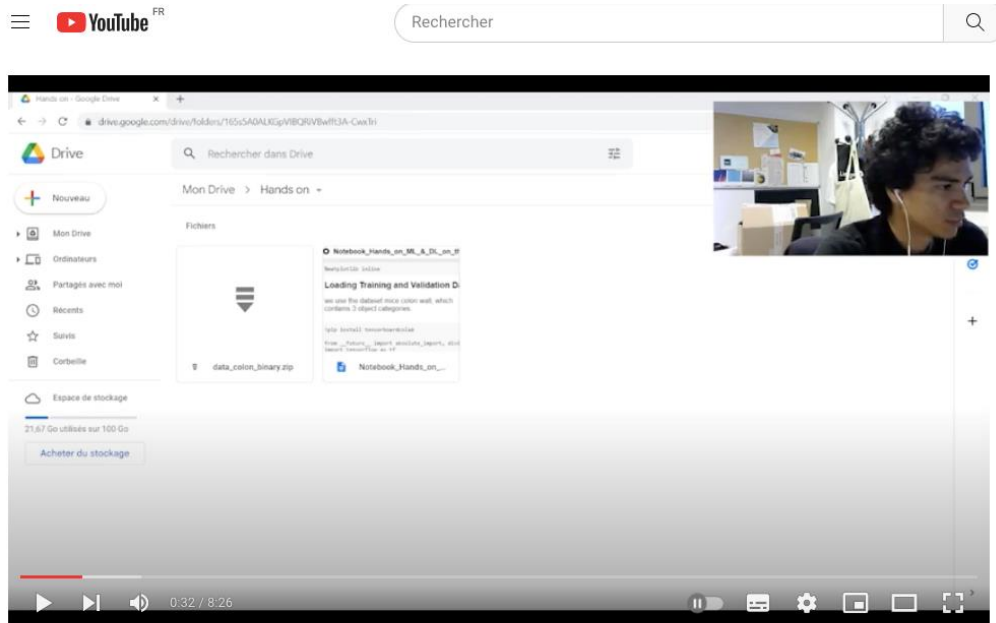
<https://www.youtube.com/watch?v=dCPv536TElw&t=46s>

# Classification Kezako ?

Tri d'images par classe par deep learning

Présenté lors de formation PHENOME

Vidéo tutoriel le disponible sur chaîne youtube par Herearii Metuarea



Hands on model classification

<https://www.youtube.com/watch?v=W2luOX6lK3w&t=31s>

## Classifieur multiclassés

Résultats préliminaires avec les annotations issues de Zooniverse

	precision	recall	f1-score	support
sporulation	0.92	0.93	0.93	113
necrosis_dots	0.82	0.38	0.52	37
necrosis_stains	0.00	0.00	0.00	22
necrosis_senescence	0.00	0.00	0.00	8
micro avg	0.91	0.66	0.77	180
macro avg	0.44	0.33	0.36	180
weighted avg	0.75	0.66	0.69	180
samples avg	0.79	0.65	0.69	180



Pas assez de disques foliaires avec des taches ou de la sénescence dans le jeu de données. Un nouveau jeu de données plus équilibré sera produit.

Le VAE trouve une frontière entre les valeurs extrêmes d'OIV sans que cette donnée ait été utilisée lors de l'entraînement



## Step 1 image acquisition



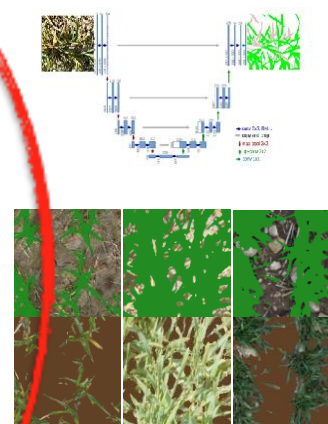
from past and future  
funded experiments

## Step 2 annotation



from collaborative  
platform

## Step 3 Deep learning

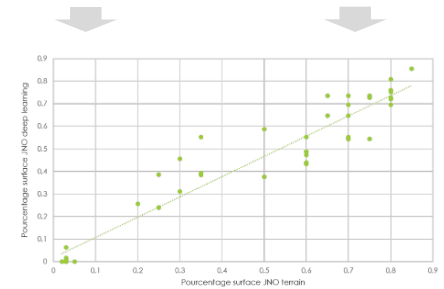


from didactic version of  
U-Net

## Step 4 Data analysis

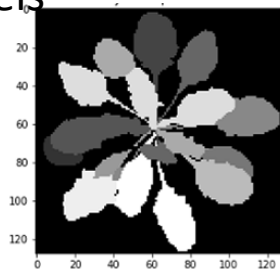


Comparison with ground truth  
Automatic cluster of types of errors

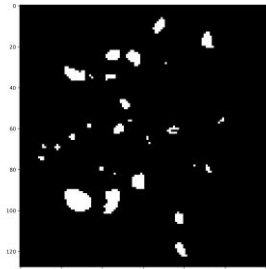
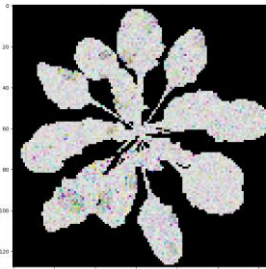


# Plant symptom segmentation

*Arabidopsis*: 783  
RGB labels



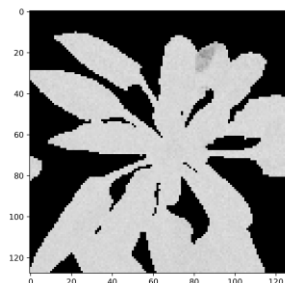
Algorithm mapping  
Gaussian noise



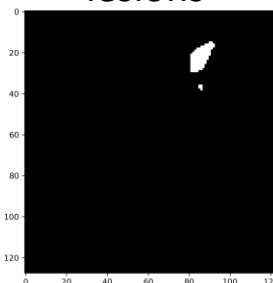
**5481** examples  
of synthetic  
fluorescent  
images of  
diseased plants  
with **automatic  
disease  
annotation**

+ Data augmentation

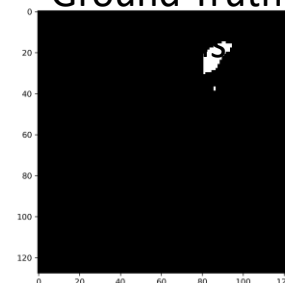
Real-Fluo-  
Diseased



Predicted  
lesions

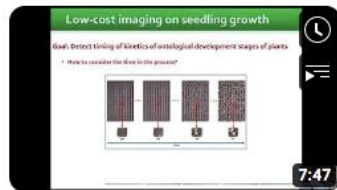


Ground Truth

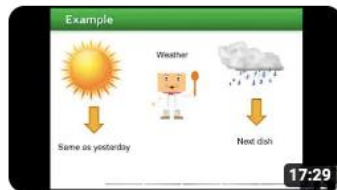


Best case: 90% recall and 97% precision

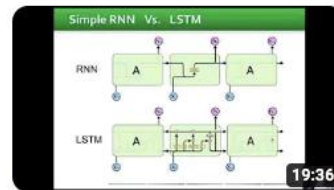
Moyen de robustifier les performances des Algos de deep learning  
Présenté lors de formation PHENOME  
Vidéo tutoriel le disponible sur chaîne youtube par David



DEEP LEARNING FULL PACK  
Introduction to RNN part 3  
30 vues • il y a 2 ans



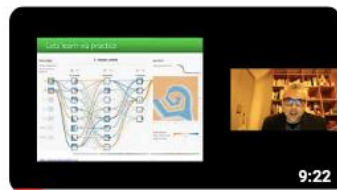
DEEP LEARNING FULL PACK  
Introduction to RNN part 1  
52 vues • il y a 2 ans



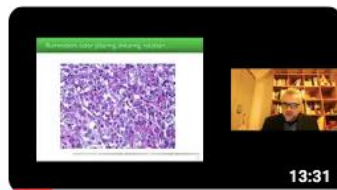
DEEP LEARNING FULL PACK  
Introduction to RNN part 2  
35 vues • il y a 2 ans



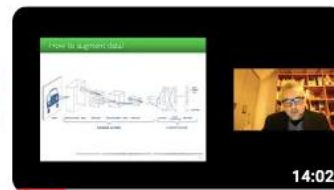
DEEP LEARNING FULL PACK  
Data augmentation part 4  
106 vues • il y a 2 ans



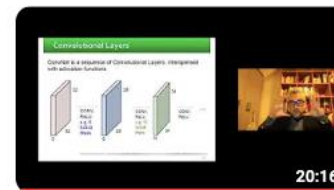
DEEP LEARNING FULL PACK  
Data augmentation part 3



DEEP LEARNING FULL PACK  
Data augmentation part 2



DEEP LEARNING FULL PACK  
Data augmentation part 1



DEEP LEARNING FULL PACK  
CNN Principles

<https://www.youtube.com/watch?v=jjVao6YDDIA&t=142s>

# Computer vision as a DIY process

Step 1 image acquisition



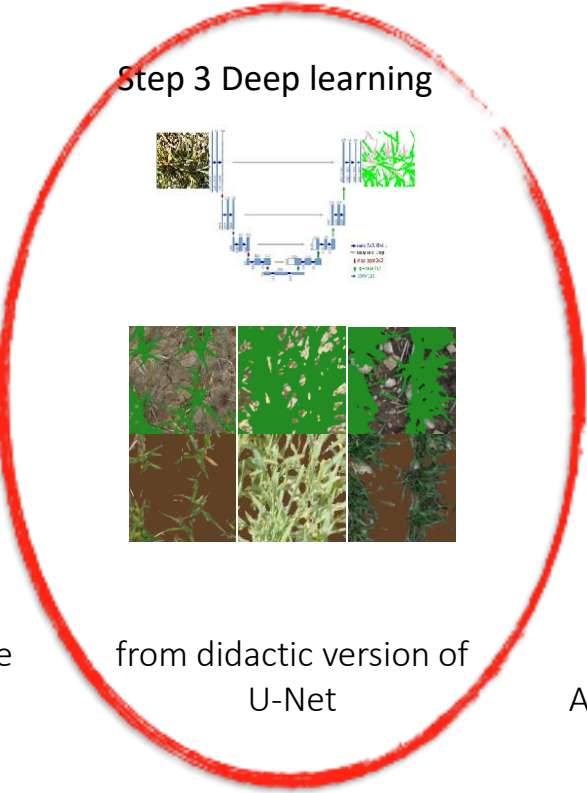
from past and future funded experiments

Step 2 annotation



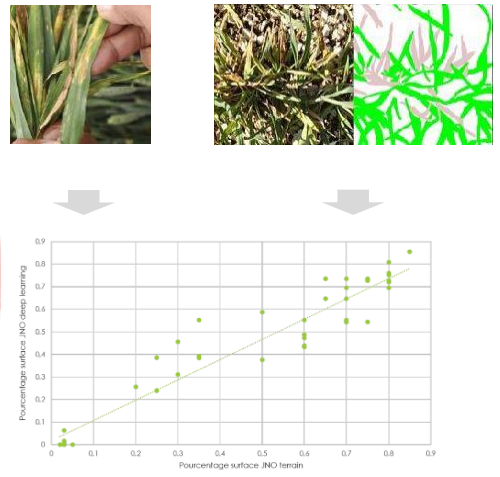
from collaborative platform

Step 3 Deep learning



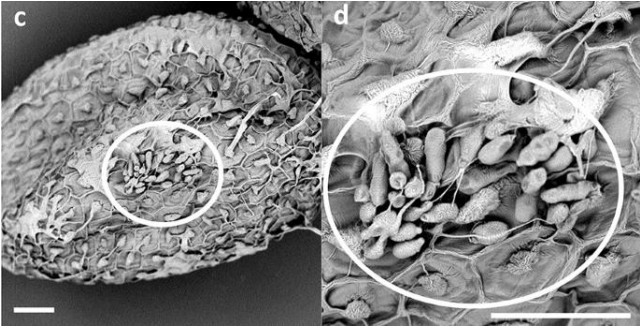
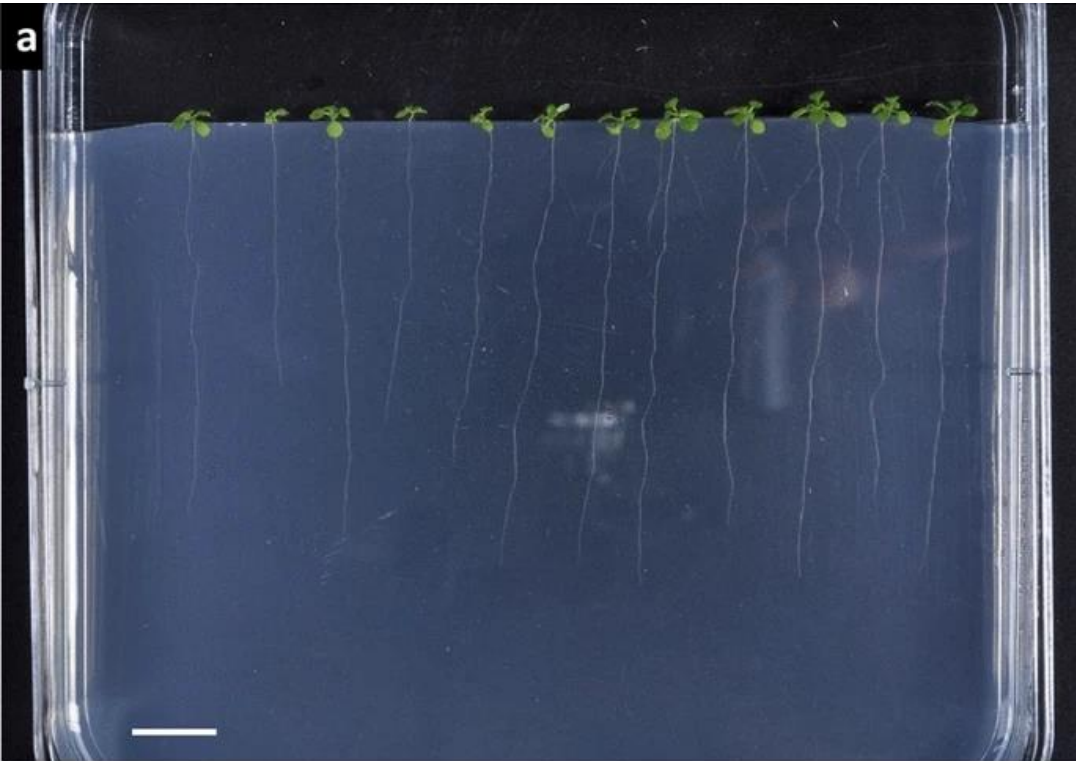
from didactic version of U-Net

Step 4 Data analysis

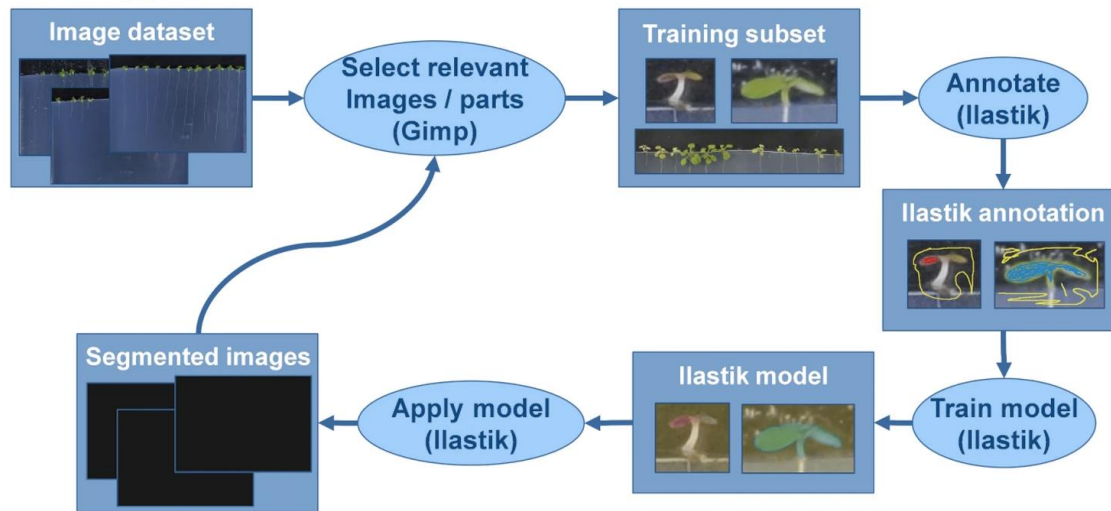


Comparison with ground truth  
Automatic cluster of types of errors

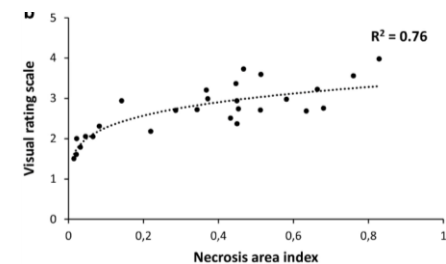
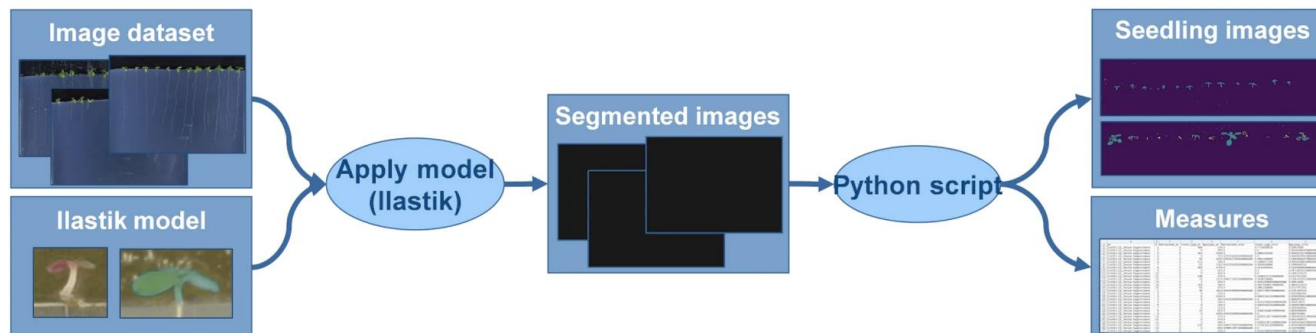
# Plant symptom segmentation with Shallow learning



## Training phase



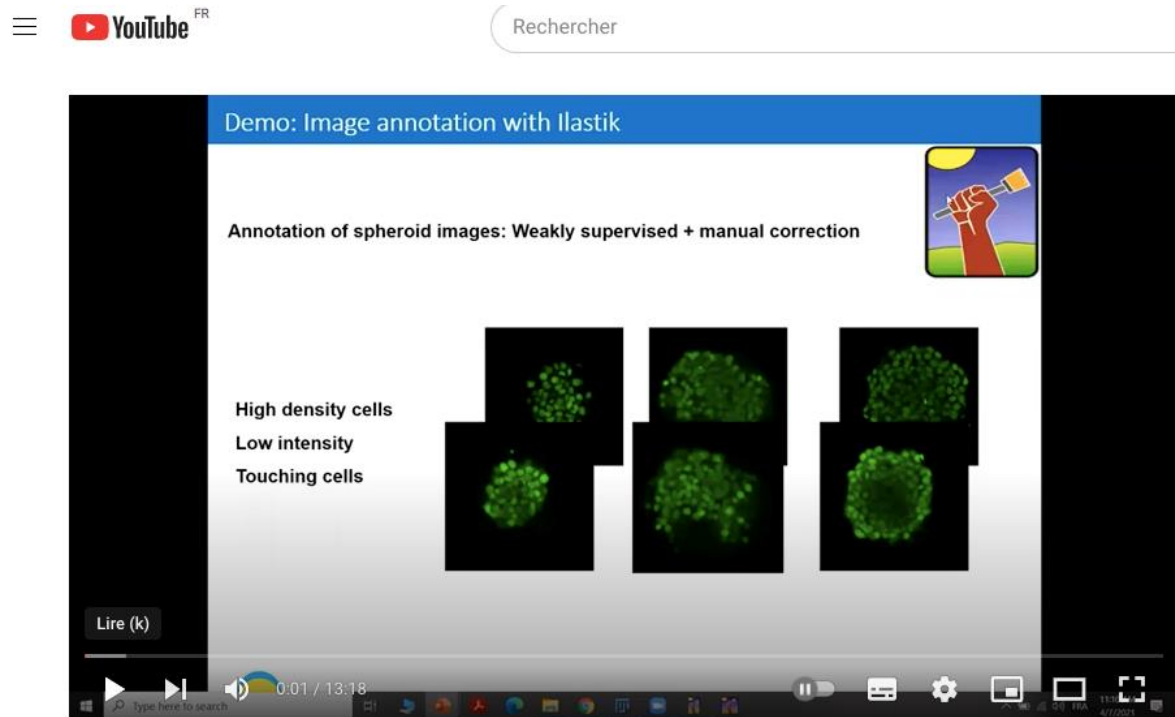
## Measurement phase



Outil libre de machine learning

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Vidéo tutoriel le disponible sur chaîne youtube par Ali Ahmad



Annotation and manual annotation in Ilastik

<https://www.youtube.com/watch?v=A3v8yrmBOvc>

# Computer vision as a DIY process

Step 1 image acquisition



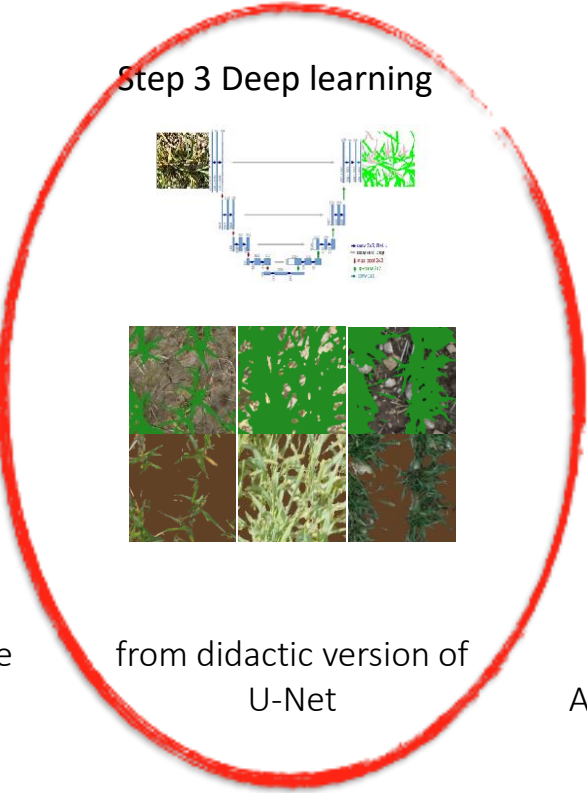
from past and future funded experiments

Step 2 annotation



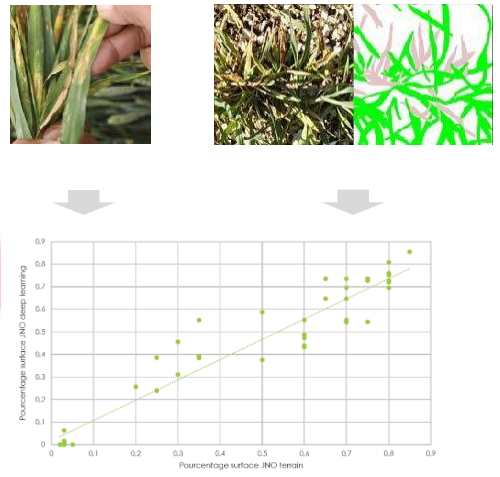
from collaborative platform

Step 3 Deep learning



from didactic version of U-Net

Step 4 Data analysis

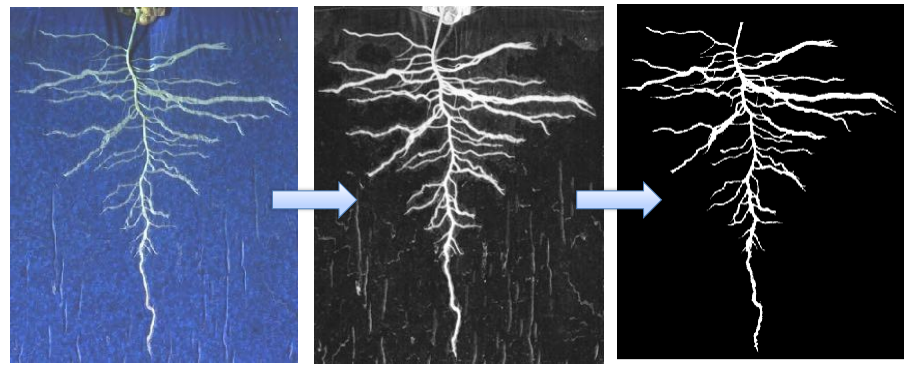


Comparison with ground truth

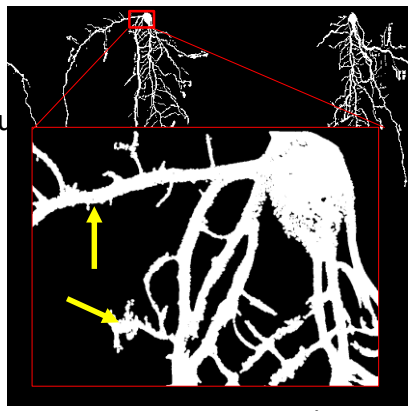
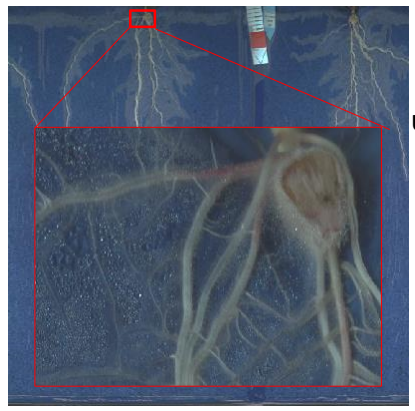


# Quantifying interactions on root

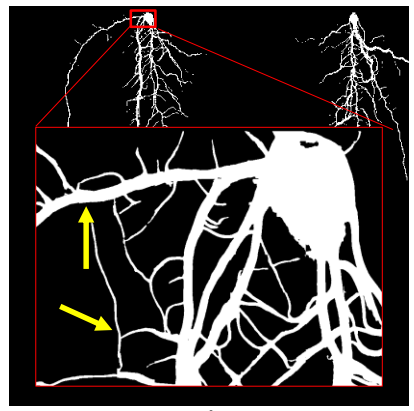
## Segmentation



- Opérationnel
- Portage EGI avec réannotation et réentraînement
- Dockerisation



computer vision classique



Deep learning

European Grid Infrastructure

Présenté lors de formation PHENOME

Vidéo tutoriel le disponible sur chaîne youtube par Herearii Metuera



Deepaas & Napari hand in hand

<https://www.youtube.com/watch?v=bc53pvzVWDs&t=12s>

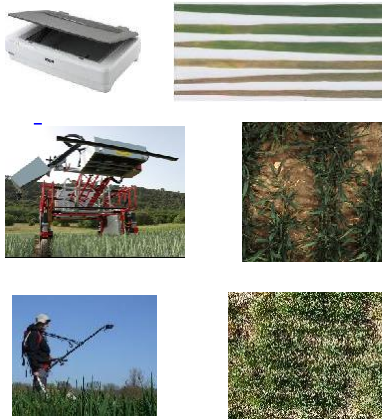
Machine virtuelle légère

Vidéo tutoriel le disponible sur chaîne youtube par Herearii Metuera



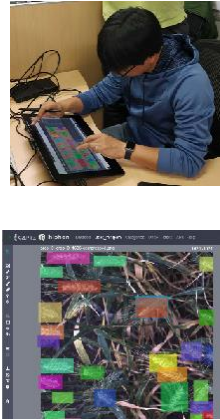
<https://www.youtube.com/watch?v=OjMwkviD3Co>

## Step 1 image acquisition



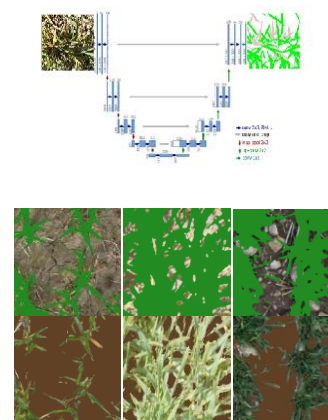
from past and future  
funded experiments

## Step 2 annotation



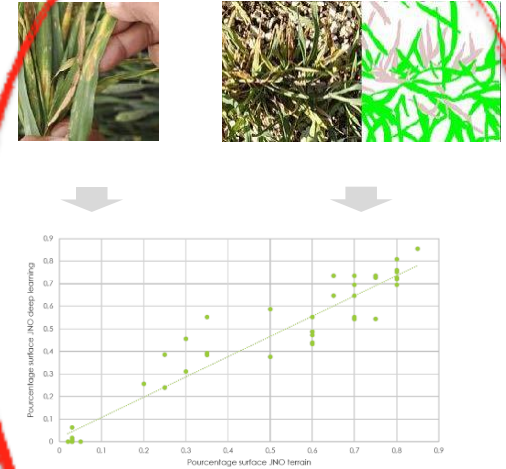
from collaborative  
platform

## Step 3 Deep learning



from didactic version of  
U-Net

## Step 4 Data analysis



Comparison with ground truth  
Automatic cluster of types of errors

Options initiales de travail :

- Utiliser des capteurs RVB haute résolution (PHENOMOBILE et LITERAL)
- Estimer la sévérité des maladies, mais pas d'identification des maladies
- Application à des maladies foliaires du blé (ici : fusariose)
- Mode d'acquisition vertical car simple



Vegetation /  
Background



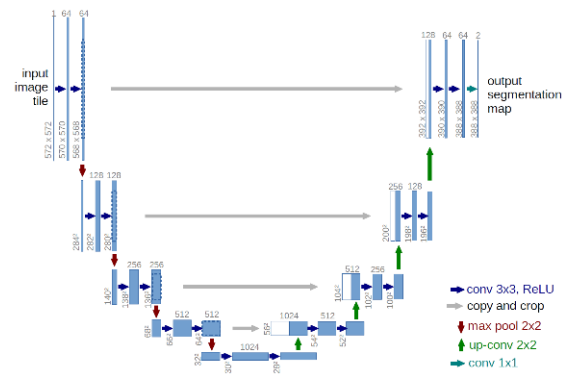
Wheat heads



Stems



Model 1

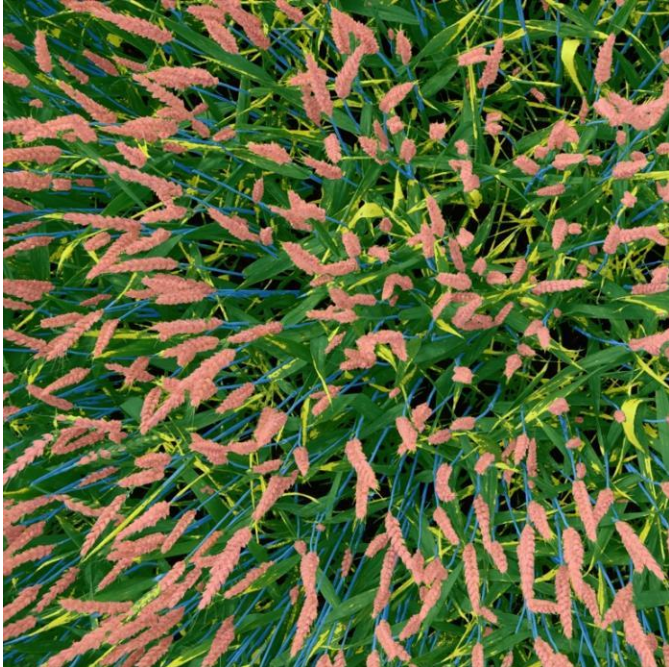


Model 2

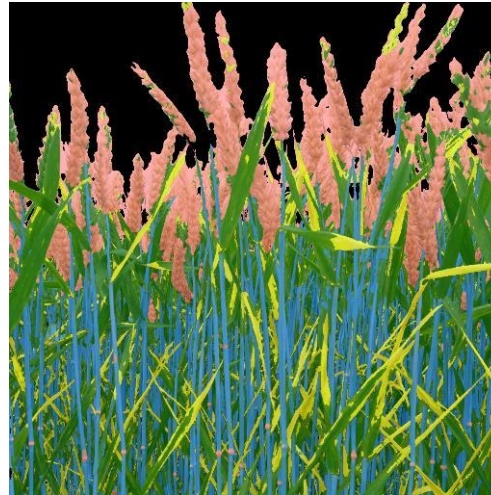


Model 3

Unet Network



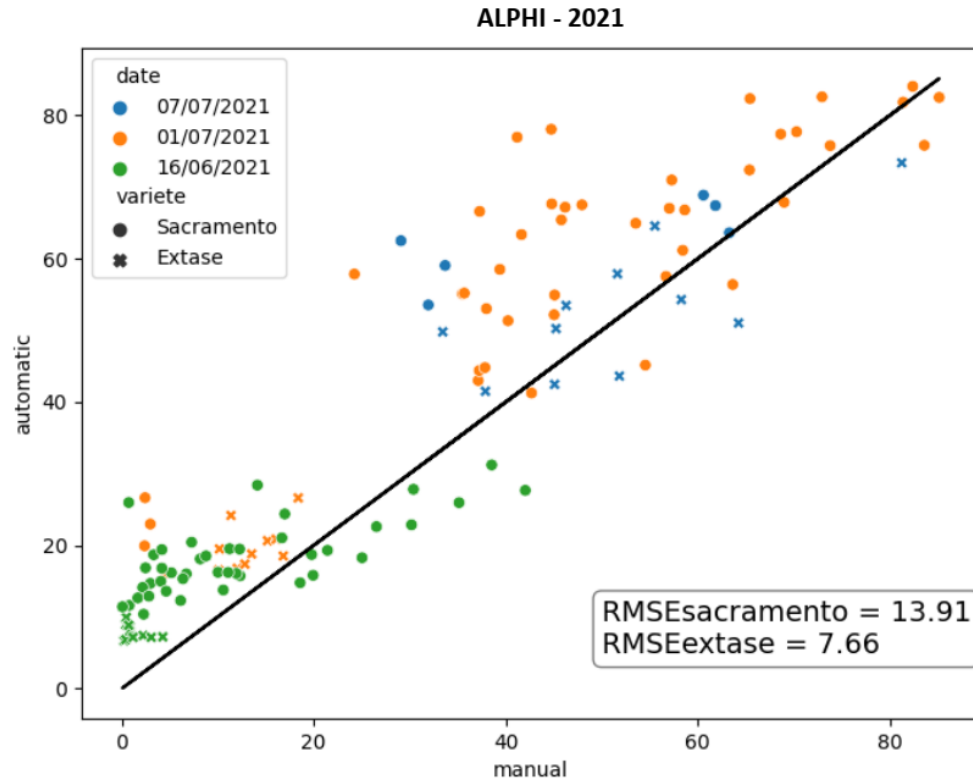
Green / Non green  
pixels segmentation  
model



-  Stems
-  Healthy leaves
-  Non green leaves
-  Wheat heads
-  Background

Disease symptoms and natural senescence are in the class 'Non green'

$$Disease = \frac{yellow\_pixels}{leaves\_pixels}$$



→ 2 varieties:

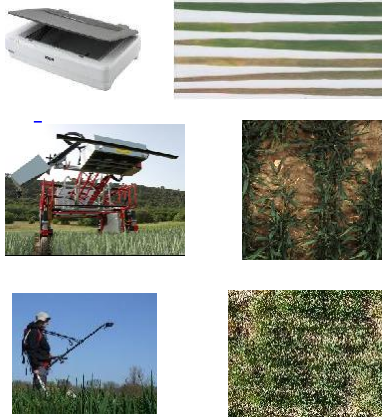
- 1 with beard (Sacramento)
- 1 without (Extase)

→ Good correlation for both case but much better for variety without beard.

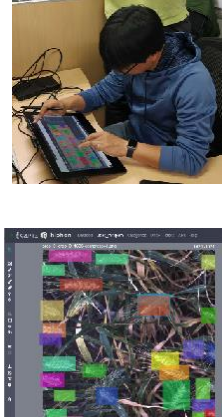


# Conclusion: CV as a DIY process

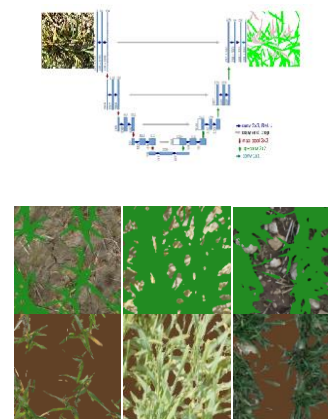
## Step 1 image acquisition



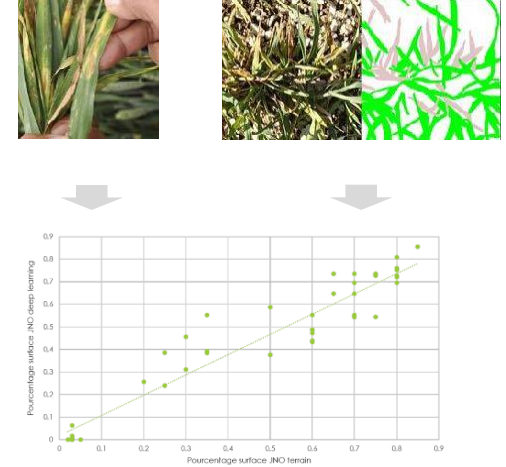
## Step 2 annotation



## Step 3 Deep learning



## Step 4 Data analysis



from past and future  
funded experiments

from collaborative  
platform

from didactic version of  
U-Net

Comparison with ground truth  
Automatic cluster of types of errors



Mon site Web



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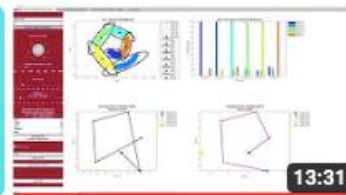
PHENOGRID



Container avec Docker



Container avec Singularity



Ordinalysis tutorial



Acquisition d'objet 3D avec Range Vision